

# Lecture 15

## 14.5 - The Chain Rule

Consider a function  $\vec{F}(x_1, \dots, x_n) = \langle f_1(x_1, \dots, x_n), \dots, f_m(x_1, \dots, x_n) \rangle$

The total derivative of  $\vec{F}$  is the matrix (an  $m \times n$  matrix)

$$D\vec{F}(x_1, \dots, x_n) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \dots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}$$

We can also take partial derivatives of  $\vec{F}$ :

$$\frac{\partial \vec{F}}{\partial x_i} = \left\langle \frac{\partial f_1}{\partial x_i}, \frac{\partial f_2}{\partial x_i}, \frac{\partial f_3}{\partial x_i}, \dots, \frac{\partial f_m}{\partial x_i} \right\rangle$$

Chain Rule: Suppose  $\vec{F}(x_1, \dots, x_n) = \langle f_1(x_1, \dots, x_n), \dots, f_m(x_1, \dots, x_n) \rangle$

and  $\vec{G}(y_1, \dots, y_p) = \langle g_1(y_1, \dots, y_p), \dots, g_n(y_1, \dots, y_p) \rangle$  and that the range of  $\vec{G}$  is inside the domain of  $\vec{F}$ . If  $\vec{G}$  is differentiable at a point  $(a_1, \dots, a_p)$  and  $\vec{F}$  is differentiable at  $\vec{G}(a_1, \dots, a_p)$ , then

$$D(\vec{F} \circ \vec{G})(a_1, \dots, a_p) = D\vec{F}(\vec{G}(a_1, \dots, a_p)) D\vec{G}(a_1, \dots, a_p)$$

Def: Let  $\vec{F}(x_1, \dots, x_n) = \langle f_1(x_1, \dots, x_n), \dots, f_m(x_1, \dots, x_n) \rangle$

be a function which is defined at  $(a_1, \dots, a_n)$  and at all points arbitrarily close to  $(a_1, \dots, a_n)$ . Then we say  $\vec{F}$  is differentiable at  $(a_1, \dots, a_n)$  if

$D\vec{F}(a_1, \dots, a_n)$  exists and

$$\lim_{\vec{h} \rightarrow \vec{0}} \frac{|\vec{F}(\vec{a} + \vec{h}) - \vec{F}(\vec{a}) - D\vec{F}(\vec{a})\vec{h}|}{|\vec{h}|} = 0.$$

Let us reduce the scope of the chain rule a bit by only considering "outside functions" whose output is a real number, i.e.,  $f = f(x_1, \dots, x_n)$ .

Chain Rule: Let  $z = f(x_1, \dots, x_n)$  and

$$\vec{G}(y_1, \dots, y_p) = \langle g_1(y_1, \dots, y_p), \dots, g_n(y_1, \dots, y_p) \rangle = \langle x_1(y_1, \dots, y_p), \dots, x_n(y_1, \dots, y_p) \rangle$$

where the range of  $\vec{G}$  is in the domain of  $f$ . If  $\vec{G}$  is differentiable at  $(a_1, \dots, a_p)$  and  $f$  is differentiable at  $\vec{G}(a_1, \dots, a_p)$  then for any  $y_i$  ( $1 \leq i \leq p$ ) we have:

~~$\frac{\partial z}{\partial y_i}$~~

$$\begin{aligned} \frac{\partial z}{\partial y_i}(a_1, \dots, a_p) &= \frac{\partial}{\partial y_i}(f \circ \vec{G})(a_1, \dots, a_p) = \nabla f(\vec{G}(a_1, \dots, a_p)) \cdot \frac{\partial \vec{G}}{\partial y_i}(a_1, \dots, a_p) \\ &= \frac{\partial f}{\partial x_1}(\vec{G}(a_1, \dots, a_p)) \frac{\partial x_1}{\partial y_i}(a_1, \dots, a_p) + \dots + \frac{\partial f}{\partial x_n}(\vec{G}(a_1, \dots, a_p)) \frac{\partial x_n}{\partial y_i}(a_1, \dots, a_p) \\ &= \frac{\partial z}{\partial x_1} \frac{\partial x_1}{\partial y_i} + \dots + \frac{\partial z}{\partial x_n} \frac{\partial x_n}{\partial y_i} \end{aligned}$$

If we write  $\vec{G}(y_1, \dots, y_p) = \langle x_1(y_1, \dots, y_p), \dots, x_n(y_1, \dots, y_p) \rangle$ ,

then

$$\frac{\partial z}{\partial y_i} = \nabla f(\vec{G}(y_1, \dots, y_p)) \cdot \frac{\partial \vec{G}}{\partial y_i} = \frac{\partial f}{\partial x_1} \frac{\partial x_1}{\partial y_i} + \dots + \frac{\partial f}{\partial x_n} \frac{\partial x_n}{\partial y_i}$$

Alright, so this looks a bit complicated, but it isn't. Let's actually compute some stuff.

Ex: Let  $z = f(x, y) = x^2 + y^2 + xy$  and suppose  $x = \sin t, y = e^t$ .

Find  $\frac{\partial z}{\partial t}$  (we actually can write  $\frac{dz}{dt}$  here since, after plugging in for  $x$  and  $y$ , we get a function of one variable).

Sol: In our case,  $\vec{G}(t) = \langle x(t), y(t) \rangle = \langle \sin t, e^t \rangle$ , so

$$\frac{d\vec{G}}{dt} = \langle \cos t, e^t \rangle. \quad \nabla f = \langle 2x + y, 2y + x \rangle, \text{ so}$$

$$\nabla f(\vec{G}(t)) = \langle 2\sin t + e^t, 2e^t + \sin t \rangle. \text{ Finally,}$$

$$\begin{aligned} \frac{dz}{dt} &= \nabla f(\vec{G}(t)) \cdot \frac{d\vec{G}}{dt} = 2\sin^2 t + e^t \sin t + 2e^{2t} + e^t \sin t \\ &= 2(\sin^2 t + e^t \sin t + e^{2t}) \end{aligned}$$



Ex: Let  $z=f(x,y)=x^2-2xy+y^2$ ,  $x=r\cos\theta$ ,  $y=r\sin\theta$

Find  $\frac{\partial z}{\partial r}$  and  $\frac{\partial z}{\partial \theta}$ .

Sol: Sometimes it's more convenient to leave  $\nabla f$  in terms of  $x$  and  $y$ , compute the required dot product, then plug in for  $x$  and  $y$ . We do this

here: First,  $\vec{G}(r,\theta) = \langle x(r,\theta), y(r,\theta) \rangle = \langle r\cos\theta, r\sin\theta \rangle$

$$\text{and } \nabla f = \langle 2x-2y, -2x+2y \rangle$$

$$\text{So, } \frac{\partial z}{\partial r} = \nabla f(\vec{G}(r,\theta)) \cdot \frac{\partial \vec{G}}{\partial r} = \langle 2x-2y, -2x+2y \rangle \cdot \langle \cos\theta, \sin\theta \rangle$$

$$= (2x-2y)\cos\theta + (-2x+2y)\sin\theta$$

$$= 2r(\cos\theta - \sin\theta)\cos\theta - 2r(\cos\theta - \sin\theta)\sin\theta$$

$$= 2r(\cos\theta - \sin\theta)^2 = 2r(1 - 2\cos\theta\sin\theta)$$

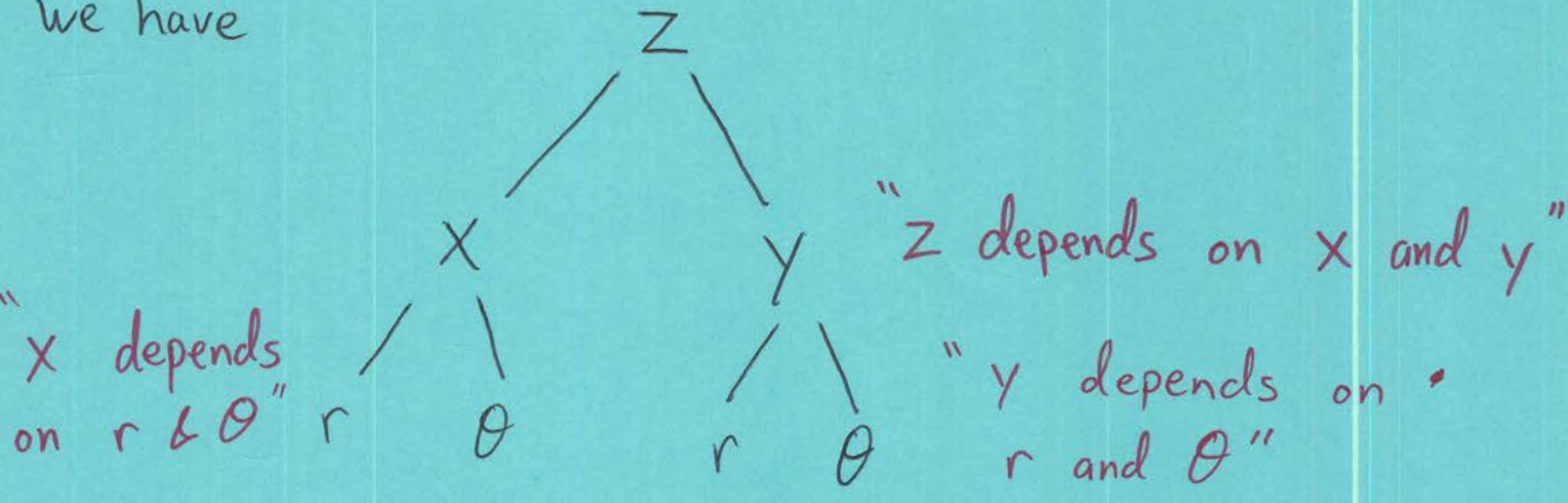
$$= 2r(1 - \sin 2\theta)$$

$$\frac{\partial z}{\partial \theta} = \nabla f(\vec{G}(r,\theta)) \cdot \frac{\partial \vec{G}}{\partial \theta} = \langle 2x-2y, -2x+2y \rangle \cdot \langle -r\sin\theta, r\cos\theta \rangle$$

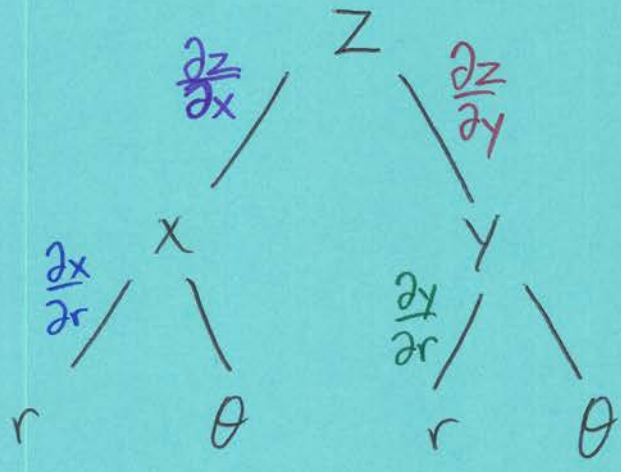
$$= (2x-2y)(-r\sin\theta) + (-2x+2y)(r\cos\theta)$$

$$= -2r^2(\cos\theta - \sin\theta)\sin\theta - 2r^2(\cos\theta - \sin\theta)\cos\theta = -2r^2(\sin^2\theta + \cos^2\theta) = -2r^2\cos 2\theta$$

There is a useful bookkeeping method we can use for finding derivatives via the chain rule, This is using dependency trees: For the last example we have



Then, to find, say  $\frac{\partial z}{\partial r}$ , we follow the paths from z to r, each edge corresponding to a derivative to be taken, then we add up paths:

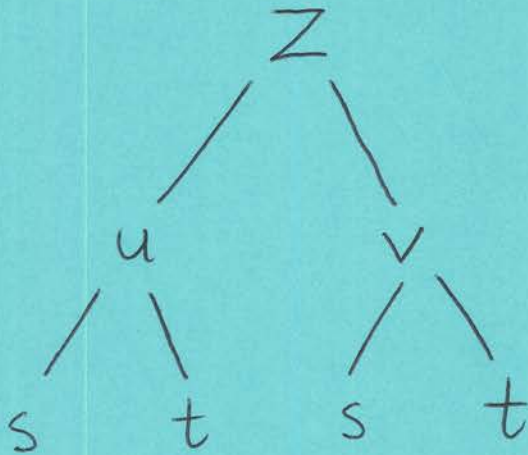


$$\frac{\partial z}{\partial r} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial r}$$

Let's see an example using this:

Ex: Find  $\frac{\partial z}{\partial s}$  and  $\frac{\partial z}{\partial t}$  where  $z = \tan\left(\frac{u}{v}\right)$  and  $u = 2s + 3t$ ,  $v = 3s - 2t$ .

Sol:



$$\text{So, } \frac{\partial z}{\partial s} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial s} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial s} \quad \left( \frac{1}{v} \sec^2\left(\frac{u}{v}\right) \right)$$

$$= \left( \frac{1}{v} \sec^2\left(\frac{u}{v}\right) \right) (2) + \left( \frac{-u}{v^2} \sec^2\left(\frac{u}{v}\right) \right) (3)$$

Plug in for  $u$  &  $v$

$$= \frac{2}{3s-2t} \sec^2\left(\frac{2s+3t}{3s-2t}\right) - \frac{3(2s+3t)}{(3s-2t)^2} \sec^2\left(\frac{2s+3t}{3s-2t}\right)$$

$$\& \frac{\partial z}{\partial t} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial t} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial t} = \left( \frac{1}{v} \sec^2\left(\frac{u}{v}\right) \right) (3) + \left( \frac{-u}{v^2} \sec^2\left(\frac{u}{v}\right) \right) (-2)$$

$$= \left( \frac{3}{v} + \frac{2u}{v^2} \right) \sec^2\left(\frac{u}{v}\right) = \frac{3v+2u}{v^2} \sec^2\left(\frac{u}{v}\right)$$

$$= \frac{3(3s-2t) + 2(2s+3t)}{(3s-2t)^2} \sec^2\left(\frac{2s+3t}{3s-2t}\right) = \frac{13s}{(3s-2t)^2} \sec^2\left(\frac{2s+3t}{3s-2t}\right) \quad \square$$